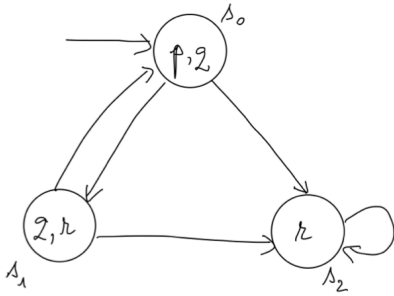


1. Does the labelled transition system \mathcal{M} from below satisfies the specification $\varphi = XGp$? Illustrate all the steps from the model checking algorithm.

\mathcal{M} :

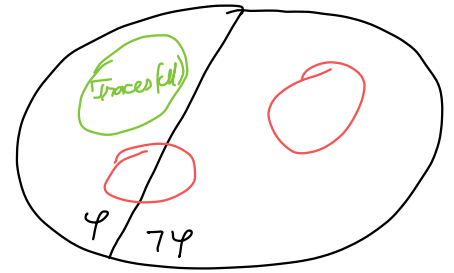


$\mathcal{M} \models \varphi$ dacă \bar{p} este π -execuție în \mathcal{M} din s_0
 avem $\pi, 0 \models \varphi$

$$\text{Traces}(\mathcal{M}) \subseteq \mathcal{L}(\varphi)$$

$$\text{Traces}(\mathcal{M}) \cap \mathcal{L}(\neg\varphi) = \emptyset$$

$$\mathcal{L}(\mathcal{A}_{\mathcal{M}} \cap \mathcal{A}_{\neg\varphi}) = \emptyset$$



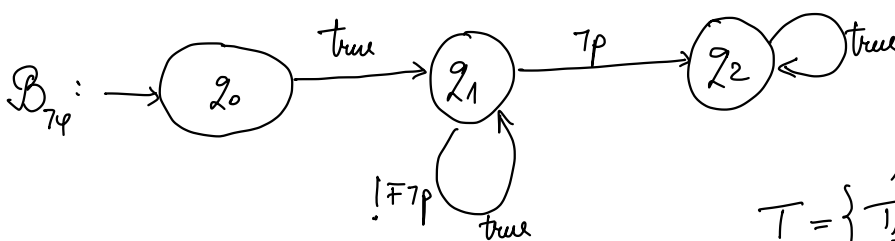
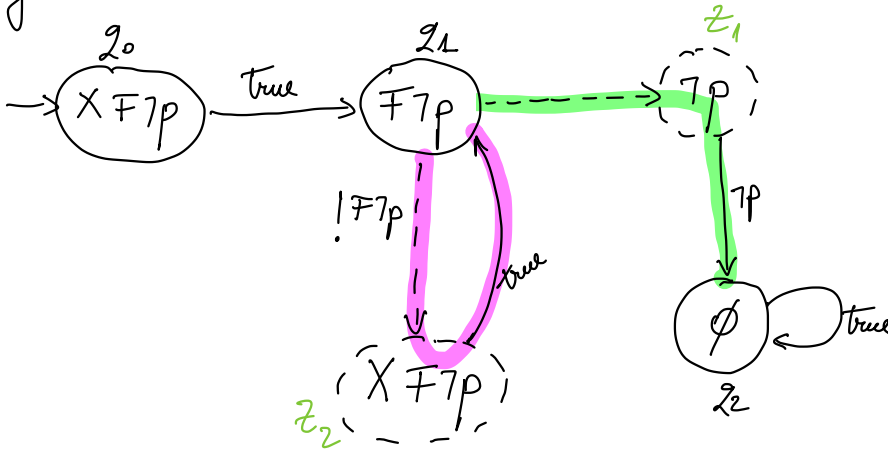
$(2^{AP})^\omega$ - toate cuv. inf. peste AP

$$\mathcal{A}_{\neg\varphi} : \neg\varphi = \neg XGp$$

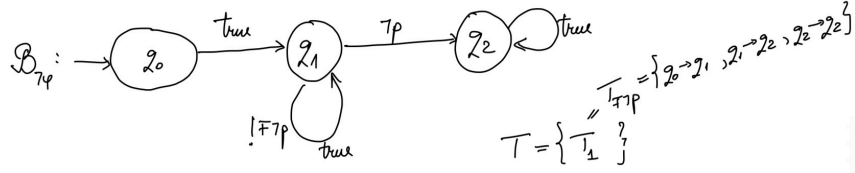
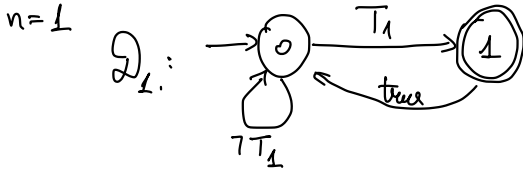
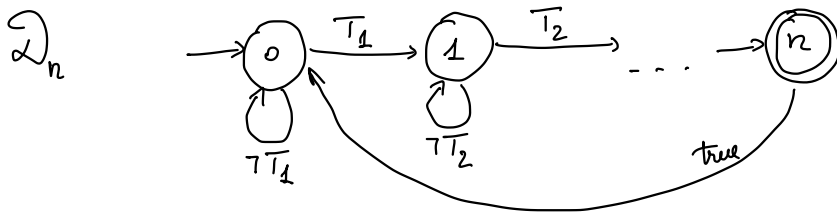
1) NNF :

$$\neg\varphi = \neg XGp \equiv X\neg Gp \equiv X\neg F\neg p$$

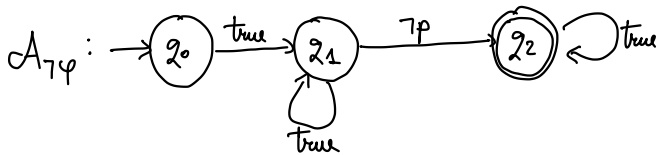
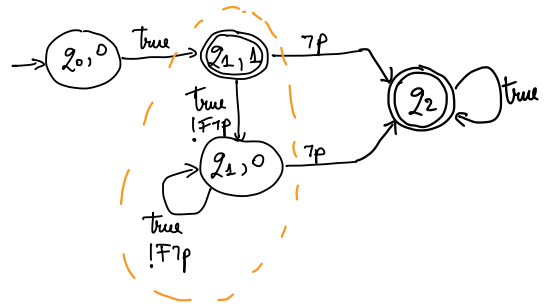
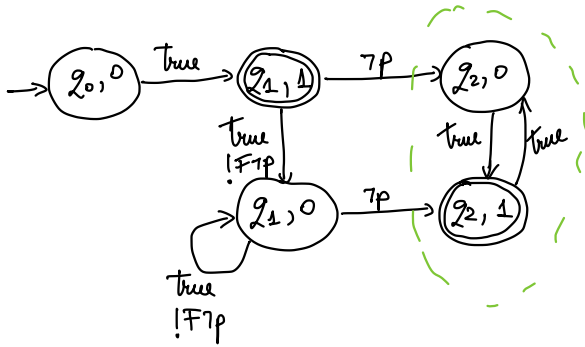
2) out generalizat



$$T = \{ \begin{matrix} \overline{T}_{\neg\varphi} \\ \overline{T}_1 \end{matrix} \} = \{ s_0 \rightarrow s_1, s_1 \rightarrow s_2, s_2 \rightarrow s_2 \}$$

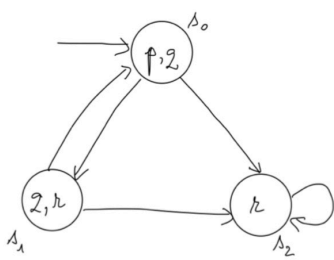


$B_{T_1} \otimes Q_1$

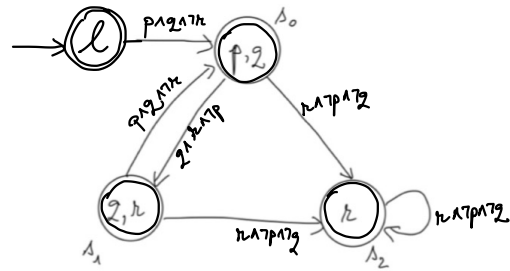


$A_{\mathcal{M}}$

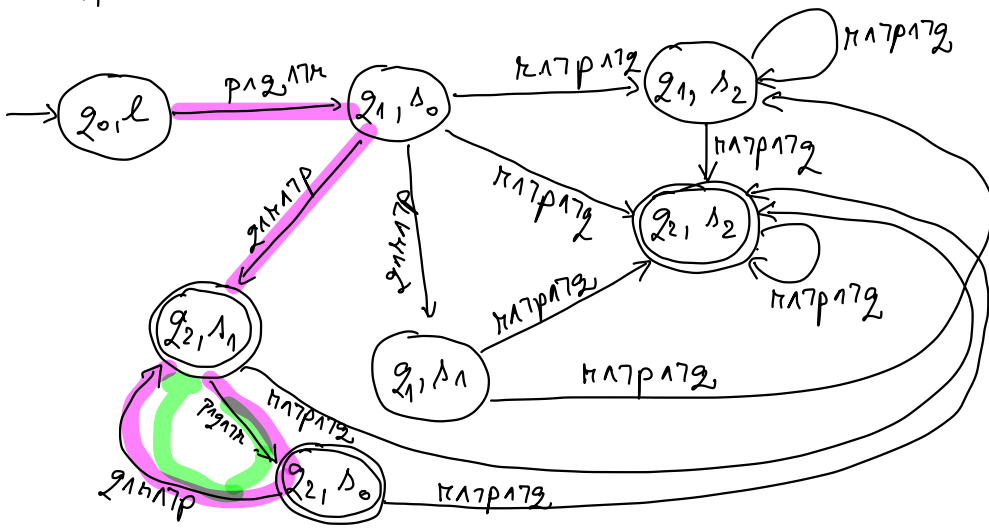
\mathcal{M} :



$A_{\mathcal{M}}$:



$A_{\mathcal{M}} \cap A_{T_1}$:



← Acceptă măcar un cuv. inf?

DA

$$\mathcal{L}(A_{\omega} \cap A_{\psi}) \neq \emptyset$$

- acceptor $\omega = \underbrace{\{p, q\}}_{\mu} \underbrace{\{r, t\}}_{(\omega)^{\omega}}$

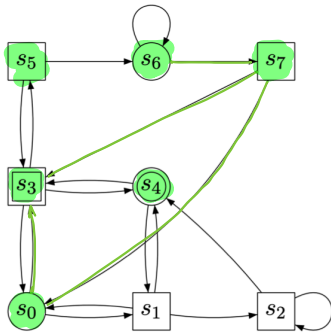
$\pi = A_0(A_1 A_0)^{\omega}$ - counterexample

$\pi, 0 \neq \psi$

Aut pt $\psi = p \cup q$

- ψ - in NNF - NO $\gamma \psi$
 - - - -
 - - - -

2. For the arena below, compute the winning region for the player controlling circles when his objective is $Reach(\{s_3, s_4\})$.



Player A : \circ - reach $(\{s_3, s_4\})$

Player B : \square

$Attr_0^A(\{s_3, s_4\}) = \{s_3, s_4\}$

$Attr_1^A(\{s_3, s_4\}) = \{s_3, s_4, s_0\}$

$Attr_2^A(\{s_3, s_4\}) = \{s_3, s_4, s_0, s_7\}$

$Attr_3^A(\{s_3, s_4\}) = \{s_3, s_4, s_0, s_7, s_6\}$

$Attr_4^A(\{s_3, s_4\}) = \{s_3, s_4, s_0, s_7, s_6, s_5\}$

$Attr_5^A(\{s_3, s_4\}) = Attr_4^A(\{s_3, s_4\}) = Attr^A(\{s_3, s_4\})$

$= Win_A(\{s_3, s_4\})$

$rank(A_3) = 0 = rank(A_4)$

$rank(A_0) = 1$

$\nabla_A: V^* V_A \rightarrow V$

$\nabla_A(\dots s_0) = s_3$

$\nabla_A(\dots s_4) = s_4$ // same twice

$\nabla_A(\dots s_6) = s_7$

$Win_B(\{s_3, s_4\}) = \{s_1, s_2\}$

Player B poate evita s_3, s_4

$\nabla_B: V^* V_B \rightarrow V$

$\nabla_B(\dots s_1) = s_2$

$\nabla_B(\dots s_2) = s_2$

$\nabla_B(\dots s_3) =$ orice