

Homework 3.1

10 points. End term: 12-th week (december 18, 2025)

1. (5.5 points) Devise an implementation (C, C++, C#, Java) for the Branch-and-Bound algorithm using the following pseudo-code:

```
 $\mathcal{S} \leftarrow \emptyset$ ; //  $\mathcal{S}$  is a stack containing LP problems of the form {objective, constraints}.
 $\mathcal{P} \leftarrow \{\max \mathbf{c}^T \mathbf{x}, \mathbf{Ax} \leq b, \mathbf{x} \geq \mathbf{0}\}$ ;
push( $\mathcal{S}, \mathcal{P}$ );
 $(\bar{\mathbf{x}}, \bar{z}) \leftarrow (\emptyset, -\infty)$ ; //  $\bar{\mathbf{x}}$  is the best current solution and  $\bar{z}$  is its corresponding objective value.
while ( $\mathcal{S} \neq \emptyset$ ) {
     $\mathcal{P} \leftarrow \text{pop}(\mathcal{S})$ ;
    if ( $\mathcal{P}$  is unbounded)
        return "unbounded problem";
    if ( $\mathcal{P}$  is feasible) { // otherwise the current problem is fathomed by infeasibility.
         $(\mathbf{x}^0, z_0) = \text{TwoPhaseMethod}(\mathcal{P})$ ; //  $\mathbf{x}^0$  is the solution of the LP relaxation and  $z_0$  is its objective values.
        if ( $z_0 > \bar{z}$ ) // otherwise the current problem is fathomed by bound.
            if ( $x_i^0 \in \mathbb{Z}, \forall i \in \mathcal{I}$ ) { // the current problem is fathomed by integrality.
                 $\bar{\mathbf{x}} \leftarrow \mathbf{x}^0$ ;
                 $\bar{z} \leftarrow z_0$ ;
            }
            else {
                find  $j \in \mathcal{I}$  such that  $x_j^0 - [x_j^0] = \max \{x_i^0 - [x_i^0] : i \in \mathcal{I}\}$ ;
                push( $\mathcal{S}, \mathcal{P} \cup \{x_j \leq [x_j^0]\}$ );
                push( $\mathcal{S}, \mathcal{P} \cup \{x_j \geq [x_j^0] + 1\}$ );
            }
        }
    }
}
if ( $(\bar{\mathbf{x}}, \bar{z}) = (\emptyset, -\infty)$ )
    return "infeasible problem";
return  $(\bar{\mathbf{x}}, \bar{z})$ ;
```

2. (3 points) Devise an implementation (C, C++, C#, Java) for a version of the Cutting-Plane algorithm using the following pseudo-code:

```
for ( $i = 0$  to  $i_{max}$ ) {
    if ( $\mathcal{P}$  is feasible) {
         $(\mathbf{x}^0, f^0) = \text{TwoPhaseMethod}(\mathcal{P})$ ;
        if ( $\mathbf{x}^0 \in \mathbb{Z}^n$ )
            return  $\mathbf{x}^0$ ;
        let  $x_i^0 \notin \mathbb{Z}$ ;
        let  $x_i + \sum_{j \in N} [\tilde{a}_{ij}] x_j \leq [\tilde{b}_i]$  be a Gomory fractional cut;
         $\mathcal{P} \leftarrow \mathcal{P} \cup \{x_i + \sum_{j \in N} [\tilde{a}_{ij}] x_j \leq [\tilde{b}_i]\}$ ;
    }
    else
        return "infeasible problem";
     $i++$ ;
}
```

3. (1.5 points) Run the Branch-and-Bound and the Cutting-Plane implemented algorithms on the following problem:

$$\begin{aligned} \min z &= \sum_{j=1}^k w_j \\ \sum_{j=1}^n x_{uj} &= 1, \quad \forall u \in V \\ x_{uj} + x_{vj} &\leq w_j, \quad \forall uv \in E, 1 \leq j \leq k \\ x_{uj}, w_j &\in \{0, 1\} \end{aligned}$$

where k is an upper bound for $\chi(G)$ (it could be n); G is one of the following graphs

- <https://cedric.cnam.fr/~porumbed/graphs/dsjc125.1.col>
- <https://cedric.cnam.fr/~porumbed/graphs/dsjc125.5.col>
- <https://cedric.cnam.fr/~porumbed/graphs/dsjc125.9.col>
- <https://cedric.cnam.fr/~porumbed/graphs/dsjc250.1.col>