

Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research

Operations Research - Lecture 6

Olariu E. Florentin

November 3, 2025

Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research

1

Integer Programming

- Introduction
- Integer Programming Models
- Totally Unimodular Matrices
 - Totally Unimodular Matrices from Bipartite Graphs
 - Totally Unimodular Matrices from Digraphs

2

Bibliography

- Many discrete optimization problems can be modeled as an **Integer Linear Programming** problem (*ILP* or simply *IP*).
- A pure ILP problem is an LP problem with the additional restriction that all variables are integer

$$\begin{aligned} & \text{maximize} && z = c^T x, \\ & \text{subject to} && Ax \leq b, \\ & && x \in \mathbb{Z}^n. \end{aligned} \tag{1}$$

- From a (more) geometric point of view an ILP problem requires to maximize (or minimize) a linear function $c^T x$ over the integer vectors of the polyhedron $\mathcal{P} = \{x \in \mathbb{R}^n : Ax \leq b\}$.
- The problem (1) can be written as
$$\max \{c^T x : x \in \mathcal{P}, x \in \mathbb{Z}^n\}. \tag{2}$$

- Sometimes such problems are *mixed*: some, but not all, of the variables are constrained to be integer and the rest of them are unrestricted.
- In this way we get the **Mixed Integer Linear Programming (MILP or MIP)** problem:

$$\begin{aligned} & \text{maximize} && z = \mathbf{c}^T \mathbf{x}, \\ & \text{subject to} && \mathbf{A}\mathbf{x} \leq \mathbf{b}, \\ & && x_i \in \mathbb{Z}, \forall i \in \mathcal{I}. \end{aligned} \tag{3}$$

where $\emptyset \neq \mathcal{I} \subsetneq \{1, 2, \dots, n\}$.

- We next present some discrete optimization problems written as integer linear programs.

Knapsack Problem

- Suppose we have a knapsack that can carry a maximum weight b and there are n types of items that we could take: an item of type i has weight $a_i > 0$.
- We want to load the knapsack with items without exceeding the knapsack capacity.
- On the other hand, suppose that an item of type i has value $c_i \geq 0$.
- The problem of loading the knapsack so as to maximize the value of all loaded items is the **knapsack problem**.

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^n c_i x_i, \\ & \text{subject to} && \sum_{i=1}^n a_i x_i \leq b, \\ & && \mathbf{x} \in \mathbb{Z}^n, \mathbf{x} \geq 0. \end{aligned} \quad (4)$$

Knapsack Problem

- If only one item of each type is allowed to be loaded, then we can use binary variables instead of general integers.

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^n c_i x_i, \\ & \text{subject to} && \sum_{i=1}^n a_i x_i \leq b, \\ & && x_i \in \{0, 1\}, \forall i = \overline{1, n}. \end{aligned}$$

- In this way we get a **Binary Integer Linear Programming (BILP** or **BIP)** problem:

$$\begin{aligned} & \text{maximize} && z = c^T x, \\ & \text{subject to} && Ax \leq b, \\ & && x \in \{0, 1\}^n. \end{aligned} \tag{5}$$

Set Packing Problem

- Suppose we have a finite set X , and a family of subsets $\mathcal{F} \subseteq 2^X$.
- A subfamily $\mathcal{F}' \subseteq \mathcal{F}$ is said to be a *packing* of \mathcal{F} if \mathcal{F}' contains only pairwise disjoint sets.
- The *Set Packing* problem is: given X , $\mathcal{F} \subseteq 2^X$, and $k \in \mathbb{N}$, there exists a packing of cardinality of least k ?
- The optimization version of this problem is the *Maximum Set Packing* problem: what is the maximum number of pairwise disjoint sets in \mathcal{F} ?

$$\begin{aligned} & \text{maximize} && \sum_{F \in \mathcal{F}} x_F, \\ & \text{subject to} && \sum_{F \in \mathcal{F}, x \in F} x_F \leq 1, \forall x \in X, \\ & && x_F \in \{0, 1\}, \forall F \in \mathcal{F}. \end{aligned}$$

(The solution x is the characteristic vector of \mathcal{F}' .)

Set Cover Problem

- A subfamily $\mathcal{F}' \subseteq \mathcal{F}$ is said to be a **covering** of \mathcal{F} if every element of X is covered by some set in \mathcal{F}' (that is, $\bigcup_{F \in \mathcal{F}'} F = X$).
- The **Set Cover** problem is: given X , $\mathcal{F} \subseteq 2^X$, and $k \in \mathbb{N}$, there exists a covering of cardinality of most k ?
- The optimization version of this problem is the **Minimum Set Cover** problem: what is the minimum cardinality covering of \mathcal{F} ?

$$\begin{array}{ll} \text{minimize} & \sum_{F \in \mathcal{F}} x_F, \\ \text{subject to} & \sum_{F \in \mathcal{F}, x \in F} x_F \geq 1, \forall x \in X, \\ & x_F \in \{0, 1\}, \forall F \in \mathcal{F}. \end{array}$$

(The solution \mathbf{x} is the characteristic vector of \mathcal{F}' .)

3-SAT Problem

- Suppose we have a finite set X of boolean variables, U the set of (positive or negative) literals over X , and C a formula in disjunctive normal form (that is, a disjunction of conjunctions of literals) where each clause is limited to at most three literals from U .
- The **3-SAT** problem is: given X and C like above, there exists an assignment of truth on X that satisfies all the clauses in C ?
- The optimization version of this problem is the **Max 3-SAT** problem: what is the maximum number of satisfiable clauses in C ?
- In order to give the LP description of this problem we define $X = \{x_1, x_2, \dots, x_k\}$, $u_i = x_i$, $v_i = \bar{x}_i$ for all $i = 1, k$, $L = \{u_i, v_i : i = 1, k\}$, and $C = \{C_1, C_2, \dots, C_p\}$, where $C_j = w_1^j \vee w_2^j \vee w_3^j$, with $w_i^j \in L$.

- The LP formulation of Max 3-SAT is

$$\text{maximize } \sum_{C \in \mathcal{C}} x_C,$$

$$\text{subject to } w_1^j + w_2^j + w_3^j - x_C \geq 0, \forall j = \overline{1, p},$$

$$u_i + v_i = 1, \forall i = \overline{1, k}$$

$$x_C \in \{0, 1\}, \forall C \in \mathcal{C},$$

$$u_i, v_i \in \{0, 1\}, \forall i = \overline{1, k}.$$

- In the corresponding truth assignment the boolean variable x_i is true iff $u_i = 1$.
- Constraint $u_i + v_i = 1$ was introduced to insure that x_i is true iff \bar{x}_i is false.
- The construction of the linear program was made such that, for an optimal solution, $x_C = 1$ iff the clause C is satisfied by the current truth assignment.

Assignment Problem

- Suppose we have n people and n tasks; every pair person/task has a certain value c_{ij} .
- The **assignment problem**: allocate exactly one person to each task so that the total value is maximized.

$$\text{maximize } \sum_{i=1}^n \sum_{j=1}^n c_{ij} x_{ij},$$

$$\text{subject to } \sum_{i=1}^n x_{ij} = 1, \forall j = \overline{1, n}$$

$$\sum_{j=1}^n x_{ij} = 1, \forall i = \overline{1, n}$$

$$x_{ij} \in \{0, 1\}, \forall i, j = \overline{1, n}.$$

Integer Programming Models

- All the problems from above, except for the last, are NP-hard problems.
- This observation implies that a typical ILP problem is hard to solve.
- The assignment problem is also called *maximum weight bipartite matching problem* and can be solved in polynomial time complexity.

- There are some classes of ILP problems which can be solved in polynomial time; this is possible for particular combinatorial problems.
- Generally we don't expect to find a polynomial time algorithm for solving an ILP problem, thus we are interested in finding broad methods to solve such a problem.
- We will study two approaches for solving ILP problems:
 - ▶ One approach is based on the particular structure of the problem (namely, particular properties of matrix A , such as *total unimodularity*);
 - ▶ The second approach is a more general one and is based on solving basic LP problems (using Simplex algorithm or other tools) and consists in several strategies: *branch-and-bound*, *cutting plane*, *branch-and-cut methods* etc.

Definition

An matrix A is called **totally unimodular** if every square submatrix of A has its determinant in the set $\{-1, 0, 1\}$.

- Obviously, a totally unimodular matrix has entries from $\{-1, 0, 1\}$.
- The following result underlines the importance of totally unimodular matrices in connection with ILP.

Theorem

Let A be a totally unimodular $m \times n$ matrix, and $b \in \mathbb{Z}^m$. Then all the extreme points of the polyhedron $\mathcal{P} = \{x \in \mathbb{R}^n : Ax \leq b\}$ are integral vectors (i. e., from \mathbb{Z}^n).

Totally Unimodular Matrices

Proof. Let x be an extreme point of \mathcal{P} and A_x be the submatrix which contains only those rows a'_j , for which $\langle a'_j, x \rangle = b_j$.

Lemma

Matrix A_x has rank n .^a

^aWe dropped the restriction concerning the full row rank of A .

Proof (for lemma). If $\text{rank}(A_x) < n$, then the n columns of A_x are linearly dependent: there exists $y \in \mathbb{R}^n, y \neq 0$ with $A_x y = 0$. Now, we can find an $\varepsilon > 0$ such that for every row a'_j which doesn't occur in A_x (i. e., $\langle a'_j, x \rangle < b_j$) we have $\langle a'_j, x + \varepsilon y \rangle \leq b_j$ and $\langle a'_j, x - \varepsilon y \rangle \leq b_j$.

Since $A_x y = 0$ and $Ax \leq b$, we get

$$A(x + \varepsilon y) \leq b \text{ and } A(x - \varepsilon y) \leq b,$$

which means that $(x + \varepsilon y), (x - \varepsilon y) \in \mathcal{P}$ - a contradiction (why?). \square

Totally Unimodular Matrices

Proof (cont'd for theorem). Let x be an extreme vector of \mathcal{P} and A_x defined as above. Since $\text{rank}(A_x) = n$, there exist a square submatrix of A_x , A_1 , of rank n . Let b_1 be a vector formed with elements of b that correspond to A_1 ; we must have $A_1 x = b_1$. Therefore, $x = A_1^{-1} b_1$; but, since $\det(A_1) = \pm 1$, $A_1^{-1} \in \mathbb{Z}^{n \times n}$, hence x is an integral vector. \square

Proposition

Let (x, y) be an extreme point of the polyhedron $\mathcal{P} = \{x \in \mathbb{R}^n, y \in \mathbb{R}_+^m : Ax + y = b\}$, then x is an extreme point of the polyhedron $\mathcal{P}' = \{x \in \mathbb{R}^n : Ax \leq b\}$.

Totally Unimodular Matrices

Proof. Let (x, y) be an extreme point of \mathcal{P} . Suppose, on the contrary, that there exist two points $x^1 \neq x^2$ in \mathcal{P}' such that

$$x = \frac{1}{2}x^1 + \frac{1}{2}x^2.$$

Let $i \in \{1, 2, \dots, m\}$; we have three cases

- (i) $y_i = 0$. We define $y_i^1 = y_i^2 = 0$.
- (ii) $y_i > 0$, $a'_i x^1 = b_i$, and $a'_i x^2 < b_i$. We define $y_i^1 = 0$ and $y_i^2 = b_i - a'_i x^2$; since $a'_i x^1 + a'_i x^2 = 2a'_i x = 2b_i - 2y_i$, we must have $y_i^2 = 2y_i$.
- (iii) $y_i > 0$, $a'_i x^1 < b_i$, and $a'_i x^2 < b_i$. We define $y_i^1 = b_i - a'_i x^1$ and $y_i^2 = b_i - a'_i x^2$; since $a'_i x^1 + a'_i x^2 = 2a'_i x = 2b_i - 2y_i$, we must have $y_i^1 + y_i^2 = 2y_i$.

Totally Unimodular Matrices

In all of the above situations we have

$$a_i^T x^1 + y_i^1 = a_i^T x^2 + y_i^2 = b_i, \text{ and } \frac{1}{2}(x_i^1, y_i^1) + \frac{1}{2}(x_i^2, y_i^2) = (x_i, y_i).$$

Obviously $(x^1, y^1) \neq (x^2, y^2)$ are points from \mathcal{P} . Since

$$\frac{1}{2}(x^1, y^1) + \frac{1}{2}(x^2, y^2) = (x, y),$$

we come to the conclusion that (x, y) cannot be an extreme point in \mathcal{P} , which is a contradiction. \square

Totally Unimodular Matrices

- An immediate consequence of Theorem 3.1 and Proposition 3.1 is the following: when we have to optimize over a polyhedron defined by a totally unimodular matrix under integral restrictions, we can use the Simplex algorithm.
- Suppose that we have to optimize over the polyhedron \mathcal{P}' . We add the slack variables y and optimize over the new polyhedron \mathcal{P} ; using the Simplex algorithm we eventually find an optimal basic feasible solution $(x, y) \in \mathcal{P}$.
- We already know that such a solution corresponds to an extreme point (x, y) of \mathcal{P} . Therefore, from Proposition 3.1, x is an extreme point and, also, an optimal solution in \mathcal{P}' .
- From Theorem 3.1, x must be an integral vector. Hence, we found an optimal solution in \mathcal{P}' which is an integral vector.

Definition

A polyhedron \mathcal{P} is integral if, for every $c \in \mathbb{R}^n$, for which $\sup\{c^T x : x \in \mathcal{P}\} \in \mathbb{R}$, the supremum is attained at an integral vector.

- A simple consequence is

Corollary

If $\mathcal{P} = \{x \in \mathbb{R}^n : Ax \leq b\}$, A is an $m \times n$ totally unimodular matrix, and $b \in \mathbb{Z}^m$, then \mathcal{P} is an integral polyhedron.

Proof. Let $c \in \mathbb{R}^n$ and x_* an optimal solution to the problem

$$\max \{c^T x : x \in \mathcal{P}\}.$$

x_* can be chosen as an extreme point of \mathcal{P} and by Theorem 3.1 such a point is integral.

Corollary

If A is an $m \times n$ totally unimodular matrix, $b \in \mathbb{Z}^m$, and $c \in \mathbb{Z}^n$, then the following primal/dual pair of problems have integral optimum solutions (if their optima are finite)

$$\max \{c^T x : Ax \leq b\} = \min \{b^T y : y \geq 0, A^T y = c\}$$

Totally Unimodular Matrices

Proof. Using Corollary 3.1 and the (easy to prove) fact that the following matrix is also totally unimodular

$$A' = \begin{bmatrix} -I_m \\ A^T \\ -A^T \end{bmatrix}.$$

- It can be proved that the property listed in Corollary 3.1 is a characterization of total unimodularity.

Theorem

(Hoffman-Kruskal Theorem) Let A be an integral $m \times n$ matrix. Then A is totally unimodular iff, for each $b \in \mathbb{Z}^m$, the polyhedron $\mathcal{P} = \{x \in \mathbb{R}_+^n : Ax \leq b\}$ is integral.

Totally Unimodular Matrices from Bipartite Graphs

- Let $G = (V, E)$ be a graph, with $V = \{v_1, v_2, \dots, v_m\}$ and $E = \{e_1, e_2, \dots, e_n\}$.
- The *incidence matrix* of G is $A \in \{0, 1\}^{m \times n}$, such that $a_{ij} = 1$ iff vertex v_i is adjacent with edge e_j .
- The incidence matrix can or cannot be totally unimodular, what we can prove is

Theorem

A graph G is bipartite iff its incidence matrix is totally unimodular.

Totally Unimodular Matrices from Bipartite Graphs

Proof.

" \implies " Suppose A' is a square submatrix of A , of order k - we prove that $\det(A') \in \{-1, 0, 1\}$ by induction on $k \geq 2$ (for $k = 1$ the result obviously holds). We have three possible situations

- (i) A' has a null column, then $\det(A') = 0$.
- (ii) A' has a column with exactly one 1. Then, using the Laplace expansion, $\det(A') = \pm 1 \cdot \det(A'')$, where A'' is a square submatrix of A' (hence, of A) of order $(k - 1)$. Therefore $\det(A'') \in \{-1, 0, 1\}$ and $\det(A') \in \{-1, 0, 1\}$.
- (iii) Every column of A' has exactly two 1's. A' is the incidence matrix of a subgraph G' of G . Since G' is also bipartite, with bipartition (V'_1, V'_2) , if we add the rows corresponding to vertices from V'_1 we get a row full of 1's, and the same result if we add the rows corresponding to vertices from V'_2 . Therefore $\det(A') = 0$.

Totally Unimodular Matrices from Bipartite Graphs

" \Leftarrow " We will use the well-known characterization: a graph is bipartite iff it doesn't contain odd cycles. If G is not bipartite, then it contains an odd cycle through vertices $v_{i_1}, v_{i_2}, \dots, v_{i_k}$, and edges $e_{j_1}, e_{j_2}, \dots, e_{j_k}$ (in this order).

The submatrix of A having rows i_1, i_2, \dots, i_k and columns j_1, j_2, \dots, j_k has the determinant equal with 2 ([check!](#)) - which is a contradiction.



- Using the last result and the Corollary 3.2, we can obtain some combinatorial results concerning bipartite graphs.
- One of these results links minimum cardinality edge covers to maximum cardinality stable sets in G ; another one relates maximum cardinality matchings to minimum vertex covers (both König's theorems).
- These results are generalized in the following theorem.

Totally Unimodular Matrices from Bipartite Graphs

Operations Research

Operations Research

Operations Research

Operations Research

Operations Research

Operations Research

Operations Research

Operations Research

Theorem

Let G be bipartite graph and $w : E(G) \rightarrow \mathbb{N}$ be a weight function defined on its edges. Then

- (i) The maximum weight of a matching in G is equal to the minimum value of $\sum_{v \in V(G)} f(v)$, where f ranges over all functions $f : V(G) \rightarrow \mathbb{N}$, such that $f(u) + f(v) \geq w(uv), \forall uv \in E(G)$.
- (ii) The minimum weight of an edge cover in G is equal to the maximum value of $\sum_{v \in V(G)} f(v)$, where f ranges over all functions $f : V(G) \rightarrow \mathbb{N}$, such that $f(u) + f(v) \leq w(uv), \forall uv \in E(G)$.

Operations Research

Operations Research

Operations Research

Operations Research

Totally Unimodular Matrices from Bipartite Graphs

Proof. The properties are equivalent with

$$\max \{w^T x : Ax \leq 1, x \geq 0\} = \min \{1^T y : A^T y \geq w, y \geq 0\},$$

$$\min \{w^T x : Ax \geq 1, x \geq 0\} = \max \{1^T y : A^T y \leq w, y \geq 0\},$$

respectively, where A is the incidence matrix of G . Now, using Theorem 3.3 and Corollary 3.2 we conclude that both these relations are true. \square

Totally Unimodular Matrices from Digraphs

- Let $D = (V, A)$ be a directed graph with $V = \{v_1, v_2, \dots, v_m\}$ and $A = \{e_1, e_2, \dots, e_n\}$. Let us define the incidence matrix of D , the $m \times n$ matrix M with entries

$$m_{ij} = \begin{cases} 1, & \text{if } e_j \text{ leaves } v_i \\ -1, & \text{if } e_j \text{ enters } v_i \\ 0, & \text{otherwise} \end{cases}$$

Theorem

The incidence matrix of a digraph is totally unimodular.

Proof. Let M' be a square submatrix of M of order k . We proceed by induction on k . Suppose $k > 2$; we have three possible situations:

Totally Unimodular Matrices from Digraphs

- (i) M' has a null column, then $\det(M') = 0$.
 - (ii) M' has a column with exactly one non-null value. Then, using the Laplace expansion, $\det(M') = \pm 1 \cdot \det(M'')$, where M'' is a square submatrix of M' (hence, of M) of order $(k-1)$. $\det(M'') \in \{-1, 0, 1\}$ by our induction hypothesis; therefore, $\det(A') \in \{-1, 0, 1\}$.
 - (iii) Every column of M' has exactly two nonzero values (an 1 and a -1). By adding up all the rows of M' we get a null row, hence $\det(M') = 0$. \square
- The incidence matrix of a digraph relates with flows and circulations in D , because the homogeneous system of linear equations $Mx = 0$ is equivalent with

$$\sum_{e_j \in \delta^+(v)} x_j = \sum_{e_j \in \delta^-(v)} x_j, \forall v \in V$$

which is the *conservation law*.

Totally Unimodular Matrices from Digraphs

Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research

Definition

Let $D = (V, A)$ be a digraph; a *circulation* of D is a function $x : A \rightarrow \mathbb{R}$ which obeys the conservation law.

Operations Research Operations Research Operations Research Operations Research

Corollary

Let $D = (V, A)$ be a digraph and $c_1, c_2 : A \rightarrow \mathbb{Z}$. There exists a circulation x of D with $c_1 \leq x \leq c_2$ iff there exists an integral circulation x of D with $c_1 \leq x \leq c_2$.

Operations Research Operations Research Operations Research Operations Research
Operations Research Operations Research Operations Research Operations Research

Proof. Obviously we need to prove just the only if part.

Totally Unimodular Matrices from Digraphs

If there exists a circulation x of D with $c_1 \leq x \leq c_2$, then the following polytope (that is, a bounded polyhedron) is nonempty

$$\mathcal{P} = \{x \in \mathbb{R}^n : Mx = 0, c_1 \leq x \leq c_2\}.$$

Any extreme point, x_* , of \mathcal{P} is an integral circulation of D , with $c_1 \leq x_* \leq c_2$. \square

- Another interesting application is the *max-flow min-cut theorem*:

Corollary

Let $D = (V, A)$ be a digraph, $s \neq t \in V$, and $c : A \rightarrow \mathbb{R}_+$ be a capacity function. The maximum value of an st -flow is equal with the minimum capacity of an st -cut.

Proof. It is obvious that the value of any st -flow cannot exceed the capacity of any st -cut. It suffices to prove that there exist a flow x and cut (S, T) such that $v(x) \geq c(S, T)$.

Let M be the vertex-arc incidence matrix of G . If we delete from M the rows corresponding to s and t , we get a matrix M' . The flow conservation law is equivalent with $M'x = 0$. Now, if a_{i_0} is the row corresponding to s , then $a_{i_0}x$ is the value of the flow x .

The maximum value of a st -flow is

$$\max \{a_{i_0}^T x : 0 \leq x \leq c, M'x = 0\}$$

The dual problem is

$$\min \{c^T y'' : y'' \geq 0, M'^T y' + y'' \geq a_{i_0}\},$$

Totally Unimodular Matrices from Digraphs

or

$$\min \{c^T y'' : y'' \geq 0, M_0^T (y'^T \ y''^T)^T \geq a_0\},$$

where







$$M_0 = \begin{bmatrix} M' \\ I_n \end{bmatrix}, a_0 = \begin{bmatrix} a_{i_0}^T \\ 0 \end{bmatrix}.$$

Obviously, M_0 is a totally unimodular matrix (why?). Since a_{i_0} is an integral vector, the optimal solution of the dual (y', y'') is an integral vector. We can build a st -cut like this:

$$S = \{v \in V : v \neq s, t, y''_v \leq -1\} \cup \{s\}, T = V \setminus S.$$

The proof is completed by observing that $v(x) \leq c(S, T)$ (exercise). \square

Bibliography

-  Bertsimas, D., J. N. Tsitsiklis, *Introduction to Linear Optimization*, Athena Scientific, Belmont, Massachusetts, 1997.
-  Chekuri, C., *Topics in Combinatorial Optimization*, University of Illinois Urbana-Champaign, Lecture Notes: <https://courses.engr.illinois.edu/cs598csc/sp2010/>, 2010.
-  Conforti, M., G. Cornuejols, G. Zambelli, *Integer Programming*, Graduate Texts in Mathematics, Springer, 2014.
-  Griva, I., S. G. Nash, A. Sofer, *Linear and Nonlinear Optimization*, 2nd edition, SIAM, 2009.
-  Schrijver, A., *A Course in Combinatorial Optimization*, Electronic Edition: homepages.cwi.nl/~lex/files/dict.pdf, 2013.
-  Vanderbei, R., J., *Linear Programming - Foundations and Extensions*, International Series in Operations Research & Management Science, Springer Science, 4th edition, 2014.